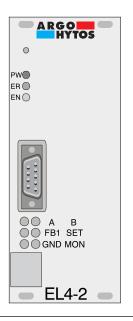


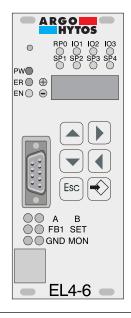
Digital Amplifier and Controller for Proportional Valves

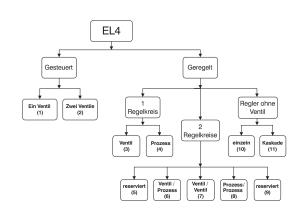
EL4

HA 9140 7/2012

Replaces HA 9140 4/2004







General Applications

The amplifier card EL4 is used for:

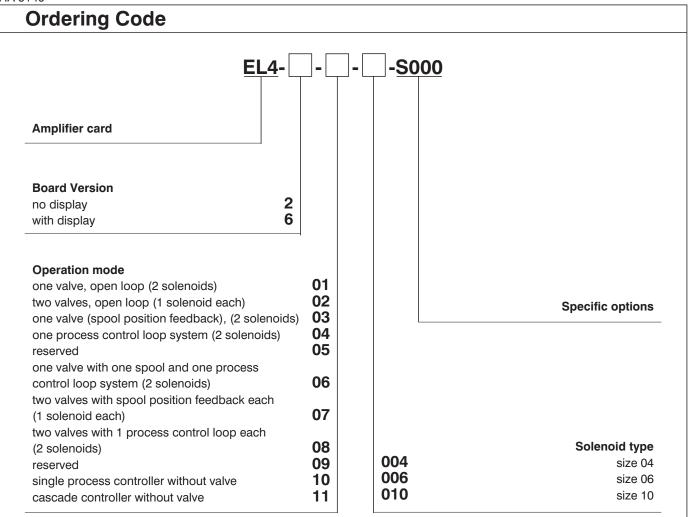
- · With or without electrical feedback transducers:
 - proportional directional valves direct and pilot operated
 - · proportional flow control valves
 - · proportional pressure reducing valves
 - proportional pressure regulating valves
 - · cartridge valves
 - servo valves with torque motors
- Controlling of hydraulic motors, installations and systems, e.g.:
 - · position
 - speed
 - pressure

- · revolutions per minute
- torque
- · power etc.
- Volume flow control and pressure control of pumps (if the occasion arrives: limitation in weight, controlling valve spool position)
- Controlling of different process values:
 - P/Q controlling
 - · pump controlling
 - · controlling of pressures
 - · controlling of pilot- and main stage
 - cascade controlling of components etc.

Features

- Fully digitized amplifier and controller with the advantage of:
 - · no on-board potentiometer
 - · no jumpers settings required
 - · digital setting and display of all parameters
 - · user safety when programming
 - no potentiometer adjustment for measurement of solenoid current
- Flexible and reliable system:
 - use of a modern 16 Bit μ C
 - · high power reserve
 - hardware and software extensions available following client's needs (e.g. bus interface, special output stages like H-bridges for servo valves or direct current motors, optional RAM on request)
 - easy software update by use of a Flash-EPROM; adaptations and extensions can be made without change to EPROM (download from PC via RS232)

- high reliability and safety through the use of a hardware watch-dog and reset module
- variable settings for magnetic systems and sensor signals making high flexibility possible
- Functional use of the interface (partly still in development):
 - change of selected parameters "on-the-fly" without interference or interrupting the controller
 - analyzation of system performance through selection of display parameters with the PC
 - a monitoring program allows direct access to amplifier with the use of external system controllers (e.g. programmable logic controllers / PLC)
 - in development: accessing different amplifiers from a PC or a controller by addressing them (using option RS485) and sending data from amplifier to amplifier (copy parameter settings)

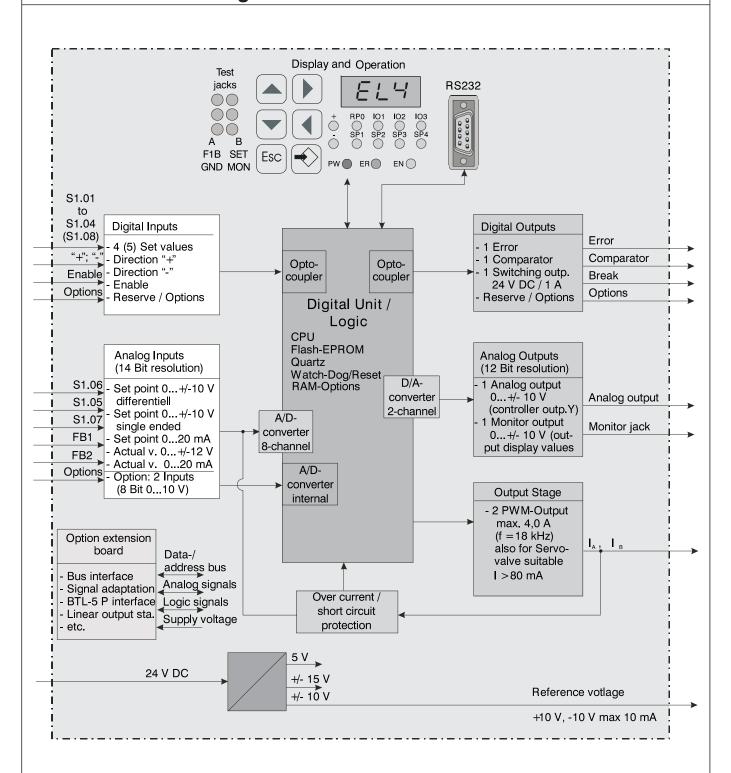


100	hnion	l Data
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Parameters	Range, characteristics
Supply voltage	DC (12) 18 30 V, residual ripple < 10 %, (12 V on request)
Solenoid systems selection	0.8 A / 1.1A / 1.3 A / 1.6 A / 2.4 A / 2.7 A / 3.5 A (others on request)
Power input	Max. 50 VA
Applicable fuse (quick)	3.15 A
Auxiliary voltage	\pm 10 V, max. load 10 mA.
Control voltage for external recallable set point	24 V \pm 10 %, residual ripple \leq 10 % current input \leq 20 mA each
Ambient temperature	32 °F 122 °F (0 °C 50 °C) (other range on request)
Storage temperature	-4 °F 140 °F (- 20 °C 60 °C)
Plug connection	DIN 41 612, 48 pol. form F gold plated
EMC	
Protection	Burst on wires as per EN 61000-4-4 HF-Field as per EN 61000-4-3 ESD as per EN 61000-4-2
Emissions	Emissions depending on power as per EN 50011 Radiated emissions as per EN 55011
Dimensions	
Front panel/ PCB	1.988 x 5.055 in. (50.5 x 128.4 mm); 10 TE / 3 HE / 3.937 x 6.299 in. (100 x 160 mm) Euro format

Technical Data		
Parameters	Range, characteristics	
Input signals		
Analogue set values	1 input, differential 14 Bit resolution, $0 \dots \pm 10 \text{ V}$ 1 input, single ended 14 Bit resolution, $0 \dots \pm 10 \text{ V}$ 1 input, single ended 14 Bit resolution, 0 or 4 20 mA (R = 250 Ohm)	
Analogue feedback (sensor input)	1 input, 14 Bit resolution, 0 ± 12 V, 0 20 mA / 4 20 mA, Offset: 3 10 V, Gain: ca. 014 (R=100 Ohm) 1 input, 14 Bit resolution, 0 ± 10 V	
Digital inputs	8 inputs, voltage level 0 V / 24 V, 10 mA (Set point 1 4, ENABLE, RAMP, SIGN +, SIGN -)	
Output signals		
Solenoid current	2 output stages for up to 3.5 A; with over-energization and quick de-energization	
Analog output	1 output, 12 Bit resolution, 0 ± 10 V; for controlling of subsequent electronic	
Monitor output	1 output, 12 Bit resolution, 0 ± 10 V; for monitoring of internal values	
Digital outputs	2 outputs, voltage level 0 V / 24 V, 10 mA (Error, Comparator)	
Test jacks	Solenoid current, sensor 1, set value, Monitor and GND	
Auxiliary voltage	± 10 V, max. load 10 mA	
	'	
Optional I/O signals	3 in or outputs, output level 24 V, input level 5 V or 24 V (5 V level for incremental sensors on request)	
Interface	RS232 or RS485 with 9-pol Sub-D connector at front panel; RS485 also at back connector available (RS485 functions in preparation)	
Display and operation		
Only at EL4-6	4 digit display, 6 buttons (up, down, left, right, enter and Esc) Status-LED's: PW (Power), ER (Error), EN (Enable), SP1 SP4 (S1.01 S1.04), RP0 (Ramp = 0), IO1 IO3	
Only at EL4-2	Status-LED's: PW (Power), ER (Error), EN (Enable)	
Frequencies and cycle times		
PWM Frequency	18 kHz	
Cycle times	Current controller ca. 0.22 msec, inner closed loop controller ca. 0.22 msec (for valve feedback), external closed loop controller 2 ca. 0.44 msec	
Accession		
Accessories	Content	
Ordering number 23144700		
	Connecting cable to PC and EL4 - 98.42 in (2.5 m)	
23144800	Connecting cable to PC and EL4 - 196.85 in (5 m)	

Hardware-Block Diagram



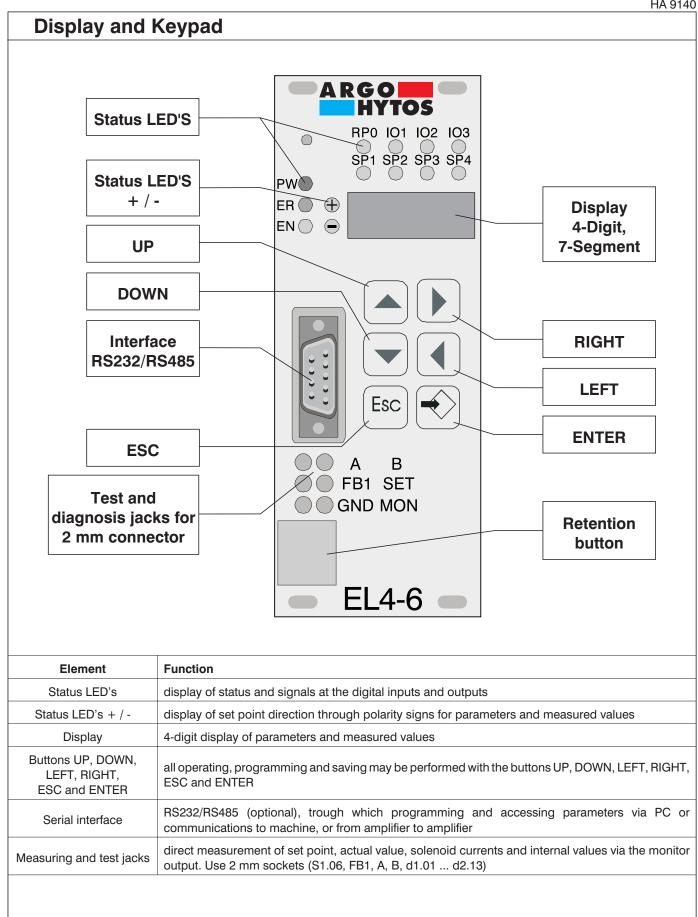
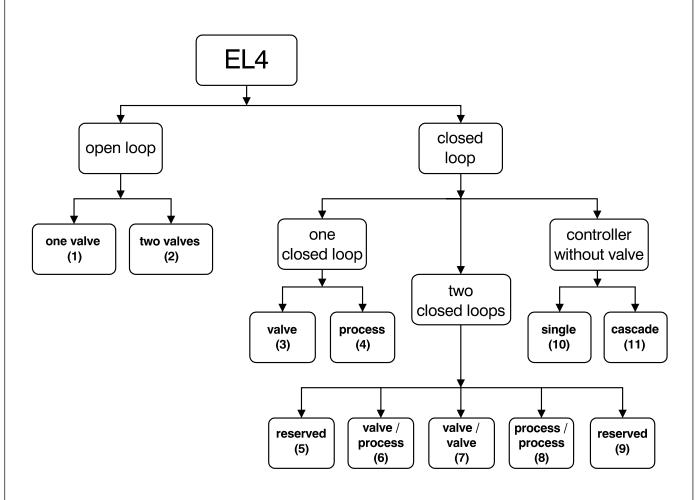
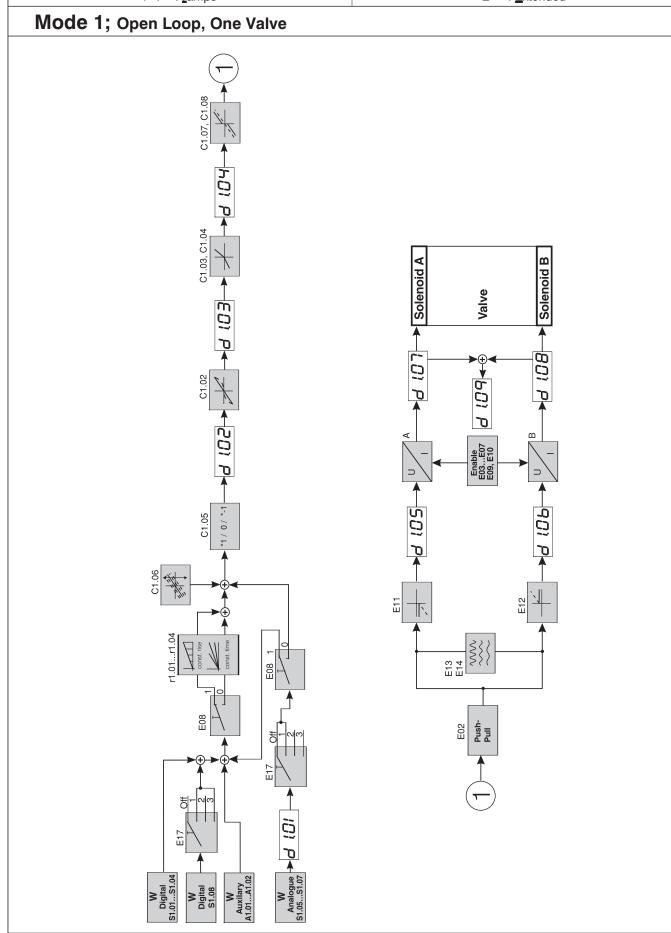


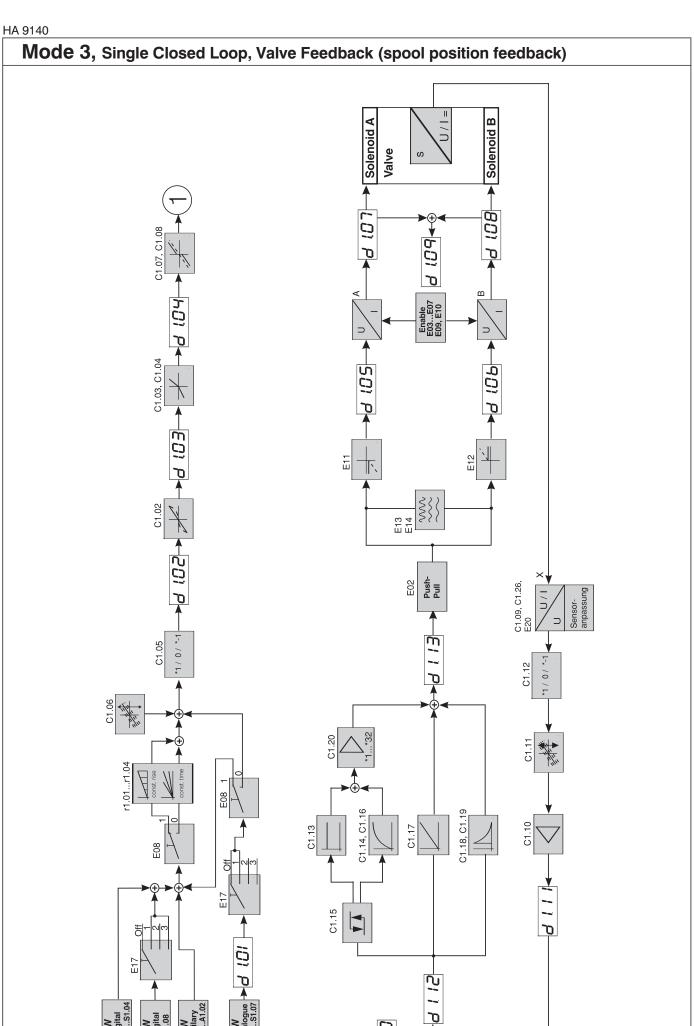
Diagram of Operation Modes



Mode	Description
1	Open loop, 1 proportional valve with 2 solenoids without feedback
2	Open loop, 2 proportional valves with 1 solenoid each without feedback
3	Closed loop valve, single, 1 proportional valve with 2 solenoids and feedback of spool position
4	Closed loop process, single, 1 proportional valve with 2 solenoids and feedback of process value (position, velocity, pressure, force, torque etc.)
5	Reserved
6	Closed loop valve and process, double, 1 proportional valve with 2 solenoids and feedback of spool position and additional feedback of process value (cascaded controller)
7	Closed loop valves, double, 2 independent proportional valve with 1 solenoid each and feedback of spool position of each valve
8	Closed loop processes, double, 2 independent proportional valve with 1 solenoid each and feedback of two independent process values (e.g. two pressure control systems)
9	Reserved
10	Controller function without valve, control of 1 process value; provide set value to follow up electronics (e.g. valve with integrated electronics, frequency converter for AC motor etc.)
11	Controller function without valve, control of 2 process values (cascaded controller, e.g. position and velocity controller); provide set value to follow up electronics (e.g. valve with integrated electronics, frequency converter for AC motor etc.)

Software Structure Diagrams Parameter setting d *.** : ₫isplay A *.** : ∆uxiliary S *.** : Set point C *.** : Controller r *.** : ramps E ** : Extended





Mode 6, Double Closed Loop, One Spool and One Process Control Loop System Controller output C2.09, C2.26, E20 C2.18, C2.19 C2.11 Solenoid B A 107 - Solenoid A 4 **→**4211>0 C2.10 80) ⊕**>**601 P Enable E03...E07 E09, E10 £ 1 H C1.09, C1.26, E20 E02 E08 1 C1.14, C1.16 C1.18, C1.19 C1.13 C1.15 21 1 P 01 I P